

## Poisson brackets

$$\pi_a \equiv \frac{\partial \mathcal{L}}{\partial \dot{\varphi}^a} \quad \text{where } a = (t, \vec{x}) \text{ etc.}$$

$$[A, B]_P \equiv \frac{\partial A}{\partial \varphi^a} \frac{\partial B}{\partial \pi_a} - \frac{\partial B}{\partial \varphi^a} \frac{\partial A}{\partial \pi_a}$$

in which the constraints are ignored during the differentiation. So  $[\varphi^a, \pi_b]_P = \delta^a_b$ .

P.B.'s are like commutators:

$$[A, B]_P = -[B, A]_P$$

$$[A, BC]_P = [A, B]_P C + B [A, C]_P$$

and

$$[A, [B, C]_P]_P + [B, [C, A]_P]_P + [C, [A, B]_P]_P = 0$$

which is Jacobi's identity.

In theories without constraints

$$[A, B] = i [A, B]_P.$$

## Constraints

Let's write the primary and secondary constraints as  $\chi_N = 0$  for  $N=1, 2, \dots$ .

The classical equation of motion for  $A$  is

$$\dot{A} = [A, H]_p,$$

and so if the  $\chi_N = 0$ , then

$$0 = \dot{\chi}_N = [\chi_N, H]_p = 0.$$

A constraint  $\chi_N$  is first class

if

$$[\chi_N, \chi_M]_p = 0$$

for all  $M$ . In  $E \& M$  both  $\Pi_0 = 0$  and  $\mathcal{H} \cdot E - J^0 = 0$  are first-class constraints.

The full set of first-class constraints

$\chi_N = 0$  is related to a group of symmetries

under which

$$\delta_{\epsilon} A \equiv \sum_{N \in \mathcal{N}} \epsilon_N [\chi_N, A]_p.$$

These are symmetries of the Hamiltonian:

Note

$$\delta_{\epsilon} H = \sum_{N \in \mathcal{N}} \epsilon_N [\chi_N, H]_p = 0$$

Since  $\mathcal{N}$  contains  $x$ , these are local symmetries.

If these  $\chi_N$ 's are first class,  $[\chi_N, \chi_M]_p = 0$ , then

we resolve them by choosing a gauge.

## Second-class constraints

After we've solved the first-class constraints by a choice of gauge, the remaining ones  $\chi_N$  are such that

$$\sum_N u_N [\chi_N, \chi_M] \neq 0$$

for all  $u_N \neq 0$ . That is,

$$C_{NM} \equiv [\chi_N, \chi_M]_p$$

is a non-singular matrix

$$\text{Det } C \neq 0.$$

These remaining constraints are second class.

They are always even in number because all  $(2n+1) \times (2n+1)$  A.S. matrices are singular. E.g.

$$\text{Det} \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} = -a(bc) + b(ac) = 0$$

Example: the massive vector field

$$\chi_{1x} = \chi_{2x} = 0$$

$$\chi_{1x} = \pi_0(\vec{x}) \quad \chi_{2x} = \partial_i \pi_i(x) - m^2 V^0(x) + J^0(x)$$

the P.b. of these is

$$[\chi_{1x}, \chi_{2y}]_p = \int_a^3 d^3z \left( \frac{\partial \pi_0(x)}{\partial V^a(z)} \frac{\partial (\nabla \cdot \pi(y) - m^2 V^0(y) + J^0(y))}{\partial \pi_a(z)} \right.$$

$$\left. - \frac{\partial (\nabla \cdot \pi(y) - m^2 V^0(y) + J^0(y))}{\partial V^a(z)} \frac{\partial \pi_0(x)}{\partial \pi_a(z)} \right)$$

$$= - \int_a^3 d^3z \int_a^3 d^3z' \delta(x-z) \frac{\partial (\nabla \cdot \pi(y) - m^2 V^0(y) + J^0(y))}{\partial V^a(z)} d^3z$$

$$= - \int_a^3 d^3z \delta(x-z) \frac{\partial (\nabla \cdot \pi(y) - m^2 V^0(y) + J^0(y))}{\partial V^0(x)} = m^2 \delta^{(3)}(\vec{x} - \vec{y})$$

$$= -C_{2y, 1x}^{\vec{y}}$$

Also  $[\chi_{1x}, \chi_{1y}]_p = 0$  and  $[\chi_{2x}, \chi_{2y}]_p = 0$

So

$$C = m^2 \begin{pmatrix} \bigcirc & \delta & \delta & \delta \\ \delta & \delta & \delta & \delta \\ \delta & \delta & \delta & \delta \\ \delta & \delta & \delta & \delta \end{pmatrix}$$

$$\det C = \delta^4 \neq 0.$$

So there are second-class constraints.

## Dirac brackets

Dirac suggested

$$[A, B] = i [A, B]_D$$

where

$$[A, B]_D \equiv [A, B]_P - [A, X_N]_P (C^{-1})^{NM} [X_M, B]_P.$$

Now

$$[B, A]_D = -[A, B]_P - [X_M, A]_P (C^{-1})^{NM} [B, X_N]_P$$

$$= -[A, B]_P - [A, X_M]_P (C^{-1})^{NM} [X_N, B]_P$$

$$= -[A, B]_P + [A, X_M]_P (C^{-1})^{MN} [X_N, B]_P$$

$$= -[A, B]_D.$$

MSO

(C is A.S.)

$$[A, BC]_D = [A, B]_D C + B [A, C]_D \quad (\text{cf. 387.1}) \quad \text{and}$$

$$[A, [B, C]_D]_D + [B, [C, A]_D]_D + [C, [A, B]_D]_D = 0$$

Also

$$\begin{aligned} [X_N, A]_D &= [X_N, A]_P - [X_N, X_M]_P (C^{-1})^{MR} [X_R, A]_P \\ &= [X_N, A]_P - C_{NM} (C^{-1})^{MR} [X_R, A]_P \\ &= [X_N, A]_P - [X_N, A]_P = 0. \end{aligned}$$

So

$$[X_N, A]_D = 0 \quad \text{for all } A.$$

Thus

$$[X_N, A] = i [X_N, A]_D = 0$$

which makes the commutators consistent with the constraints  $X_N = 0$ .

$$\begin{aligned}
[A, BC]_D &= [A, BC]_P - [A, X_N]_P \tilde{C}^{iNM} [X_M, BC]_P \\
&= [A, B]_P C + B [A, C]_P - [A, X_N]_P \tilde{C}^{iNM} \left( [X_M, B]_P C + B [X_M, C]_P \right) \\
&= [A, B]_D C + B [A, C]_D
\end{aligned}$$

And as long as  $\{X_{\alpha} = 0\}$  and  $\{X_{\beta} = 0\}$  define the same submanifold of phase space, then

$$[A, B]_D = [A, B]_{D'}.$$

Moreover Masikawa and Nakajima have shown that from any set  $\psi^a, \pi_a$  with second-class constraints  $X_{\alpha} = 0$ , there is a canonical transformation\* to the variables  $Q^m, q^r$  and  $P_m, p_s$  such that  $\{X_{\alpha} = 0\} \Leftrightarrow q^r = p_s = 0$ . In the new coordinates, with  $X_{1n} = \delta^n$   $X_{2s} = p_s$  we have

$$C_{1v, 2s} = [q^r, p_s]_p = \delta^r_s$$

$$C_{1v, 1s} = [q^r, q^s]_p = 0$$

$$C_{2v, 2s} = [p_r, p_s]_p = 0$$

and for any  $A, B$

$$[A, X_{1n}]_p = [A, q^r]_p = -\frac{\partial A}{\partial p_r}$$

$$[A, X_{2s}]_p = [A, p_s]_p = \frac{\partial A}{\partial q^s}.$$

Now

$$C = \begin{pmatrix} 0 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ & & & & 1 \\ & & & & & 0 \end{pmatrix} \quad C^{-1} = -C = \begin{pmatrix} 0 & & & & \\ & -1 & & & \\ & & -1 & & \\ & & & -1 & \\ & & & & -1 \\ & & & & & 0 \end{pmatrix}$$

\*i.e., Poisson brackets unchanged

$$[\chi_{2n}, B]_p = [p_n, B]_p = - \frac{\partial B}{\partial q_n}$$

$$[\chi_{1n}, B]_p = [q_n, B]_p = \frac{\partial B}{\partial p_n}$$

So the Dirac

bracket  $[A, B]_D$  is

$$[A, B]_D = [A, B]_p - [A, \chi_n]_p (C^{-1})^{nm} [\chi_m, B]_p$$

$$[A, B]_D = [A, B]_p + [A, \chi_{1n}]_p [\chi_{2n}, B]_p$$

$$- [A, \chi_{2n}]_p [\chi_{1n}, B]_p$$

$$= [A, B]_p + \left( - \frac{\partial A}{\partial p_n} \right) \left( - \frac{\partial B}{\partial q_n} \right) - \frac{\partial A}{\partial q_n} \frac{\partial B}{\partial p_n}$$

$$= \sum_n \frac{\partial A}{\partial Q^n} \frac{\partial B}{\partial P_n} - \frac{\partial B}{\partial Q^n} \frac{\partial A}{\partial P_n} = [A, B]_{pR}$$

or  
↓

In terms of these variables, the Dirac bracket is the Poisson bracket computed with only the restricted set of canonical variables  $Q_n, P_n$ .

Example: MVE  $\chi_{1\vec{x}} = \Pi_0(\vec{x})$   $\chi_{2\vec{x}} = \nabla \cdot \vec{\Pi}(\vec{x})$

$$\chi_{2\vec{x}} = \nabla \cdot \vec{\Pi}_0(\vec{x}) - m^2 V^0(\vec{x}) + J^0(\vec{x})$$

$$C_{1x, 2y} = -C_{2y, 1x} = [\chi_{1x}, \chi_{2y}]_p = m^2 \delta(\vec{x} - \vec{y})$$

$$(C^{-1})^{1x, 2y} = - (C^{-1})^{2y, 1x} = -m^{-2} \delta(\vec{x} - \vec{y})$$



Thus

$$[A, B] = i[A, B]_p - i \int [A, \pi_0(z)]_p (-m^2 \delta(z-w))$$

$$+ i \int d^3z d^3w [ \nabla \cdot \pi(w) - m^2 V^0(w) + J^0(w), B ]_p d^3z d^3w$$

$$- i \int d^3z d^3w [A, \nabla \cdot \pi(w) - m^2 V^0(w) + J^0(w)]_p (+im^2 \delta(z-w))$$

$$[ \pi_0(z), B ]_p$$

$$= i[A, B]_p + im^2 \int d^3z [A, \pi_0(z)]_p [ \nabla \cdot \pi(z) - m^2 V^0(z) + J^0(z), B ]_p$$

$$- im^2 \int d^3z [A, \nabla \cdot \pi(z) - m^2 V^0(z) + J^0(z)]_p [ \pi_0(z), B ]_p$$

Now  $[V^\mu(x), \pi_\nu(y)]_p = \delta(x-y) \delta^\mu_\nu$

$$[V^\mu, V^\nu] = [\pi_\mu, \pi_\nu] = 0$$

So let's compute

$$[V^i(x), V^0(y)] = i[V^i(x), V^0(y)]_p$$

$$+ im^2 \int d^3z [V^i(x), \nabla \cdot \pi(z)]_p [\pi_0(z), V^0(y)]_p$$

$$= -im^2 \int d^3z \delta^i_j \partial_j \delta(x-z) (-1) \delta(z-y)$$

$$= im^2 \int d^3z \partial^i \delta(x-z) \delta(z-y)$$

$$= -im^2 \int d^3z \partial_i^x \delta(x-z) \delta(z-y)$$

$$= -im^2 \delta_i \delta(x-y)$$

This agrees with

$$[V^i(x), V^0(y)] = [V^i(x), m^{-2} (\nabla \cdot \pi)^0]$$

$$= m^{-2} \nabla_j^y [V^i(x), \pi_j(y)]$$

$$= m^{-2} \partial_j^y i \delta(x-y) = -i m^{-2} \partial_j^y \delta(x-y).$$

So we just assume  $[Q^m, P_m] = i \delta_m^m \delta(x-y)$

and use constraints to evaluate the other commutators involving the  $C^m$ 's.